

# CMPE 150/L : Introduction to Computer Networks

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Lecture 16

# Final project demo

- ❑ Please do the demo next week to the TAs.
- ❑ So basically you may need to finish all project functions by next week.
- ❑ Or you are allowed to use screenshots for demo. **However the screenshots MUST be consistent to your program results, or you cannot get demo points**

# Course evaluation

- ❑ Increasing the response rate is important!
- ❑ You may complete the course evaluation at any time
- ❑ Or, please bring your e-device to the class next Tuesday. I will finish the lecture 15 mins earlier and you may use the time for course evaluation.

# Chapter 5: Link layer, LANs: outline

5.1 introduction, services

5.2 error detection,  
correction

5.3 multiple access  
protocols

5.4 LANs

- addressing, ARP
- Ethernet
- switches
- VLANs

5.5 link virtualization:  
MPLS

5.6 data center  
networking

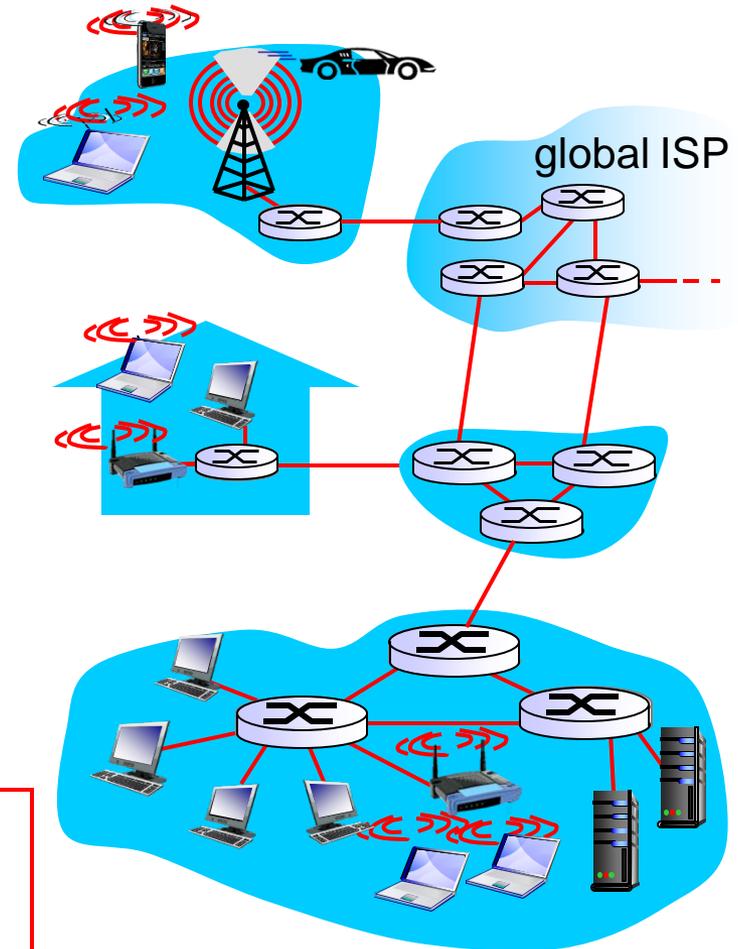
5.7 a day in the life of a  
web request

# Link layer: introduction

## *terminology:*

- ❖ hosts and routers: **nodes**
- ❖ communication channels that connect adjacent nodes along communication path: **links**
  - wired links
  - wireless links
  - LANs
- ❖ layer-2 packet: **frame**, encapsulates datagram

*data-link layer* has responsibility of transferring datagram from one node to *physically adjacent* node over a link



# Link layer: context

- ❖ datagram transferred by different link protocols over different links:
  - e.g., Ethernet on first link, frame relay on intermediate links, 802.11 on last link
- ❖ each link protocol provides different services
  - e.g., may or may not provide rdt over link

## *transportation analogy:*

- ❖ trip from Santa Cruz to Suzhou
  - limo: Santa Cruz to SFO
  - plane: SFO to PVG (Shanghai)
  - train: Shanghai to Suzhou
- ❖ tourist = **datagram**
- ❖ transport segment = **communication link**
- ❖ transportation mode = **link layer protocol**
- ❖ travel agent = **routing algorithm**

# Link layer services

## ❖ *framing, link access:*

- encapsulate datagram into frame, adding header, trailer
- channel access if shared medium
- “MAC” addresses used in frame headers to identify source, dest
  - different from IP address!

## ❖ *reliable delivery between adjacent nodes*

- we learned how to do this already (chapter 3)!
- seldom used on low bit-error link (fiber, some twisted pair)
- Used in wireless links: high error rates
  - **Q:** why both link-level and end-end reliability?
  - **A:** Reduce the frequency of end-end retrx

# Link layer services (more)

## ❖ *flow control:*

- pacing between adjacent sending and receiving nodes

## ❖ *error detection:*

- errors caused by signal attenuation, noise.
- receiver detects presence of errors:
  - signals sender for retransmission or drops frame

## ❖ *error correction:*

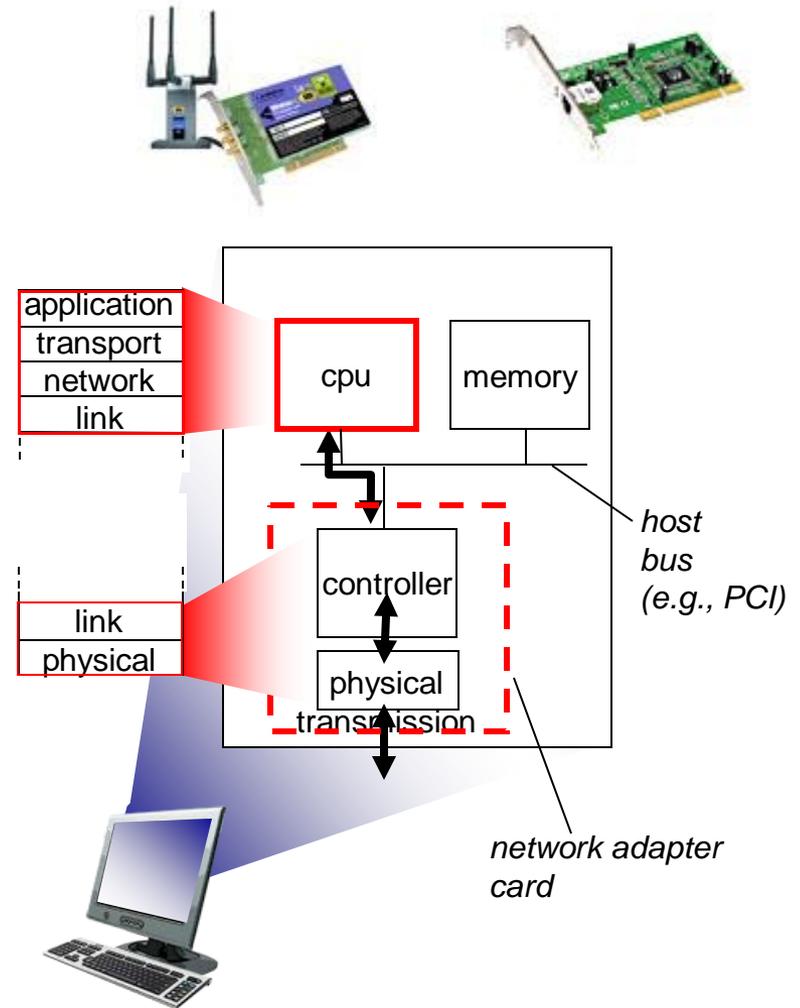
- receiver identifies *and corrects* bit error(s) without resorting to retransmission

## ❖ *half-duplex and full-duplex*

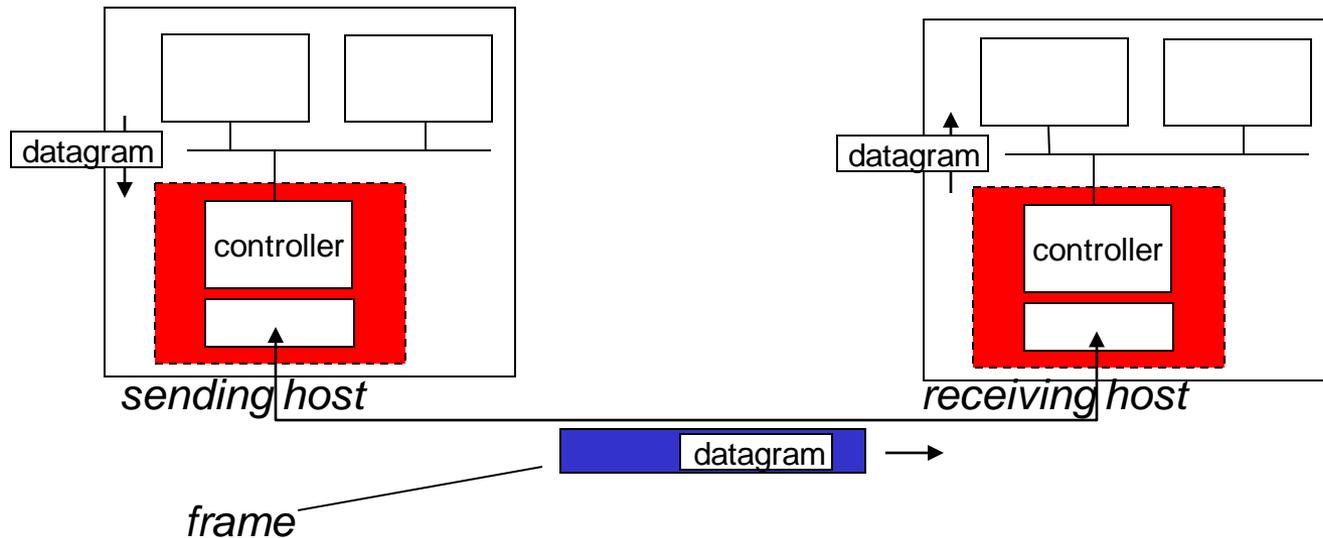
- with half duplex, nodes at both ends of link can transmit, but not at same time

# Where is the link layer implemented?

- ❖ in each and every host
- ❖ link layer implemented in “adaptor” (aka *network interface card* NIC) or on a chip
  - Ethernet card, 802.11 card; Ethernet chipset
  - implements link, physical layer
- ❖ attaches into host's system buses
- ❖ combination of hardware, software, firmware



# Adaptors communicating



## ❖ sending side:

- encapsulates datagram in frame
- adds error checking bits, rdt, flow control, etc.

## ❖ receiving side

- looks for errors, rdt, flow control, etc
- extracts datagram, passes to upper layer at receiving side

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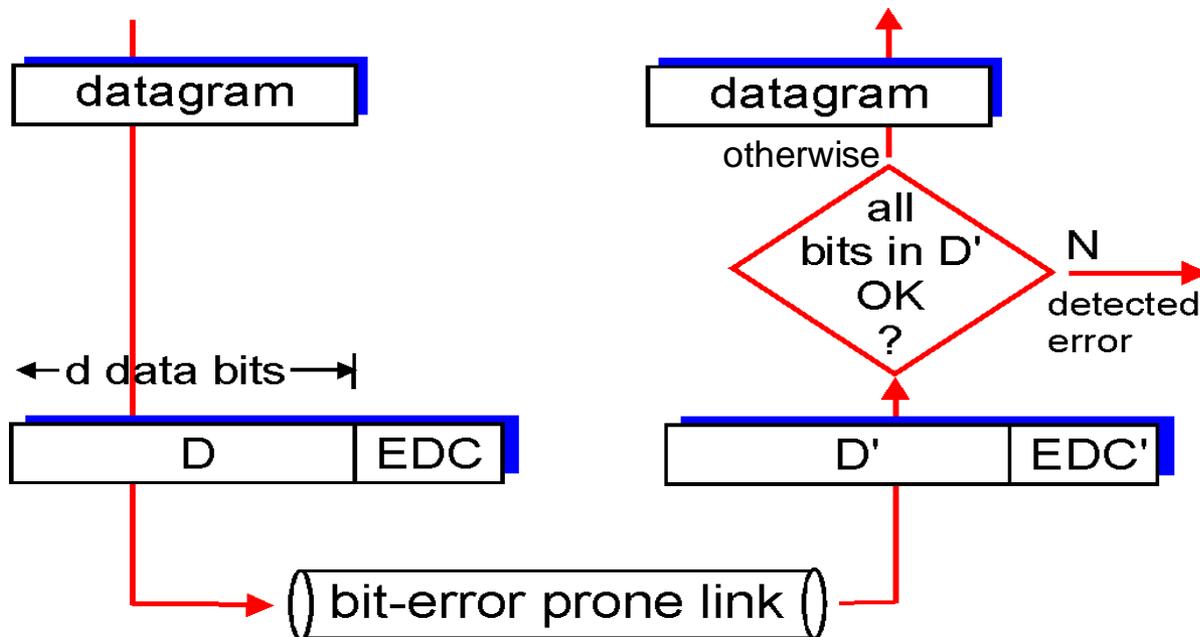
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# Error detection

EDC= Error Detection and Correction bits (redundancy)

D = Data protected by error checking, may include header fields

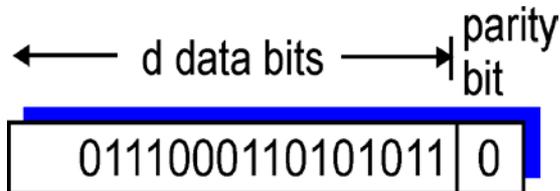
- Error detection not 100% reliable!
  - protocol may miss some errors, but rarely
  - larger EDC field yields better detection and correction



# Parity checking

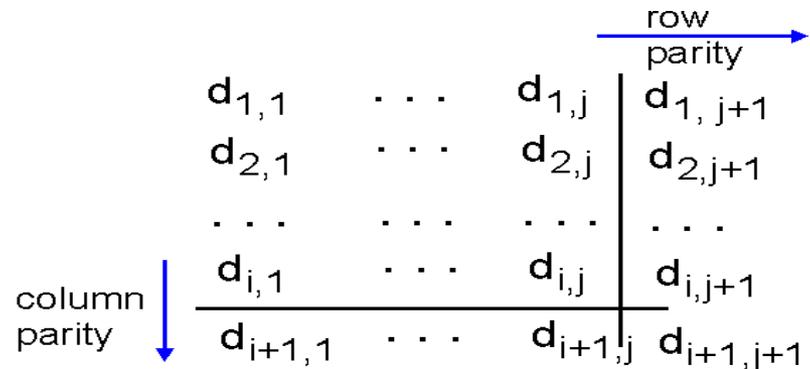
## single bit parity:

- ❖ detect single bit errors



## two-dimensional bit parity:

- ❖ detect and correct single bit errors



1	0	1	0	1	1
1	1	1	1	0	0
0	1	1	1	0	1
0	0	1	0	1	0

*no errors*

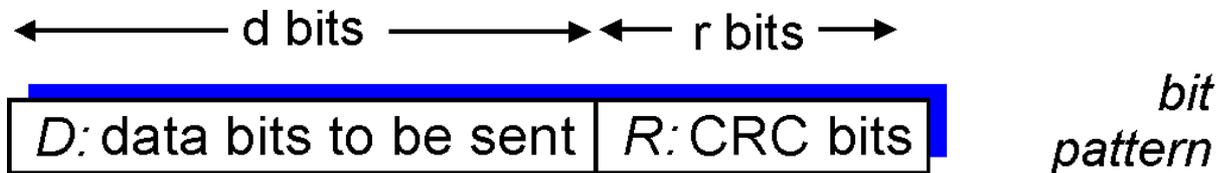
1	0	1	0	1	1
1	0	1	1	0	0
0	1	1	1	0	1
0	0	1	0	1	0

parity error

*correctable  
single bit error*

# Cyclic redundancy check

- ❖ more powerful error-detection coding
- ❖ view data bits, **D**, as a binary number
- ❖ choose  $r+1$  bit pattern (generator), **G**
- ❖ goal: choose  $r$  CRC bits, **R**, such that
  - $\langle D, R \rangle$  exactly divisible by  $G$  (modulo 2)
  - receiver knows  $G$ , divides  $\langle D, R \rangle$  by  $G$ . If non-zero remainder: error detected!
  - can detect all burst errors less than  $r+1$  bits
- ❖ widely used in practice (Ethernet, 802.11 WiFi, ATM)



$$D * 2^r \text{ XOR } R$$

*mathematical formula*

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# Multiple access links, protocols

two types of “links”:

## ❖ point-to-point

- PPP for dial-up access
- point-to-point link between Ethernet switch, host

## ❖ *broadcast (shared wire or medium)*

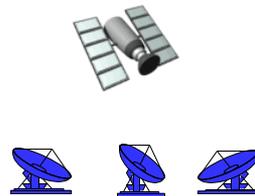
- old-fashioned Ethernet
- upstream HFC
- 802.11 wireless LAN



shared wire (e.g.,  
cabled Ethernet)



shared RF  
(e.g., 802.11 WiFi)



shared RF  
(satellite)



humans at a  
cocktail party  
(shared air, acoustical)

# Multiple access protocols

- ❖ single shared broadcast channel
- ❖ two or more simultaneous transmissions by nodes:  
interference
  - *collision* if node receives two or more signals at the same time

## *multiple access protocol*

- ❖ distributed algorithm that determines how nodes share channel, i.e., determine when node can transmit
- ❖ communication about channel sharing must use channel itself!
  - no out-of-band channel for coordination

# An ideal multiple access protocol

*given:* broadcast channel of rate  $R$  bps

*desiderata:*

1. when one node wants to transmit, it can send at rate  $R$ .
2. when  $M$  nodes want to transmit, each can send at average rate  $R/M$
3. fully decentralized:
  - no special node to coordinate transmissions
  - no synchronization of clocks, slots
4. simple

# MAC protocols: taxonomy

three broad classes:

## ❖ *channel partitioning*

- divide channel into smaller “pieces” (time slots, frequency, code)
- allocate piece to node for exclusive use

## ❖ *random access*

- channel not divided, allow collisions
- “recover” from collisions

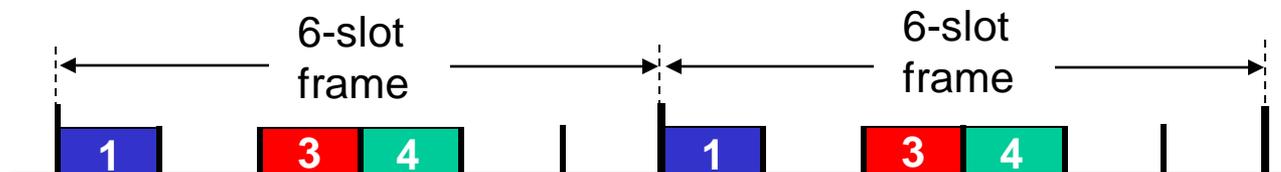
## ❖ *“taking turns”*

- nodes take turns, but nodes with more to send can take longer turns

# Channel partitioning MAC protocols: TDMA

## TDMA: time division multiple access

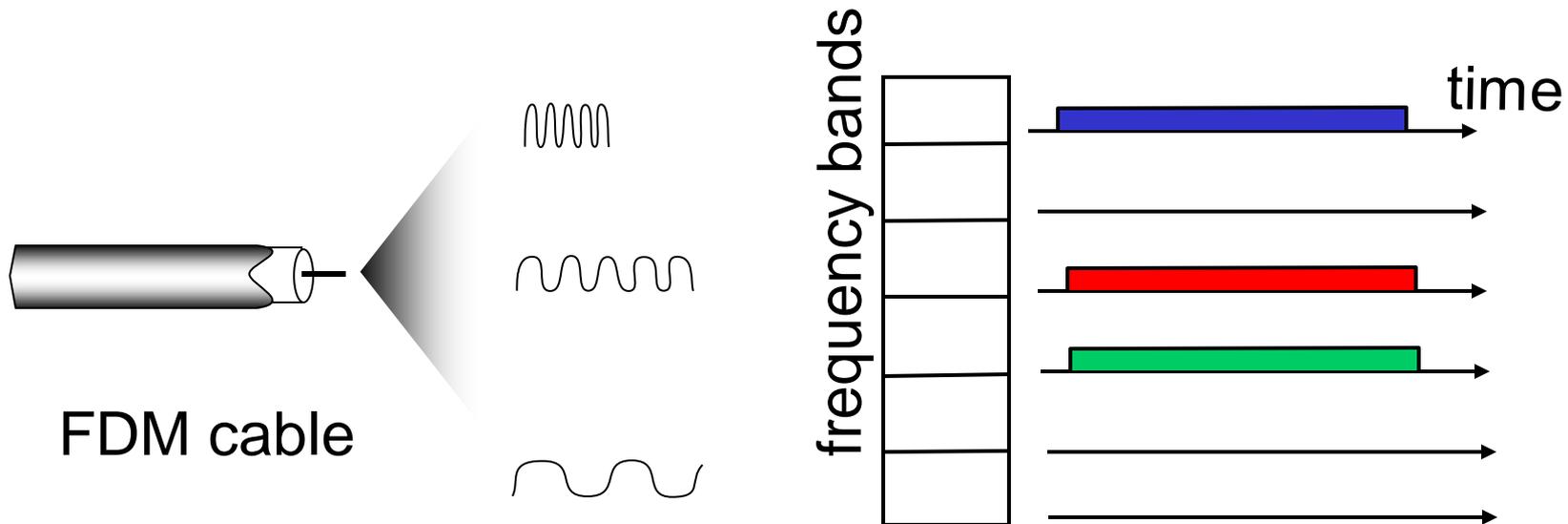
- ❖ access to channel in "rounds"
- ❖ each station gets fixed length slot (length = pkt trans time) in each round
- ❖ unused slots go idle
- ❖ example: 6-station LAN, 1,3,4 have pkt, slots 2,5,6 idle



# Channel partitioning MAC protocols: FDMA

## FDMA: frequency division multiple access

- ❖ channel spectrum divided into frequency bands
- ❖ each station assigned fixed frequency band
- ❖ unused transmission time in frequency bands go idle
- ❖ example: 6-station LAN, 1,3,4 have pkt, frequency bands 2,5,6 idle



# Channel partitioning

- ❖ Like traffic lights. Each direction has fixed time to go.
- ❖ Problem: if one station has nothing to send at its time slot or frequency, this resource cannot be used by others and is wasted.

# Random access protocols

- ❖ when node has packet to send
  - transmit at full channel data rate  $R$ .
  - no *a priori* coordination among nodes
- ❖ two or more transmitting nodes → “collision”,
- ❖ **random access MAC protocol** specifies:
  - how to detect collisions
  - how to recover from collisions (e.g., via delayed retransmissions)
- ❖ examples of random access MAC protocols:
  - slotted ALOHA
  - ALOHA
  - CSMA, CSMA/CD, CSMA/CA

# Slotted ALOHA

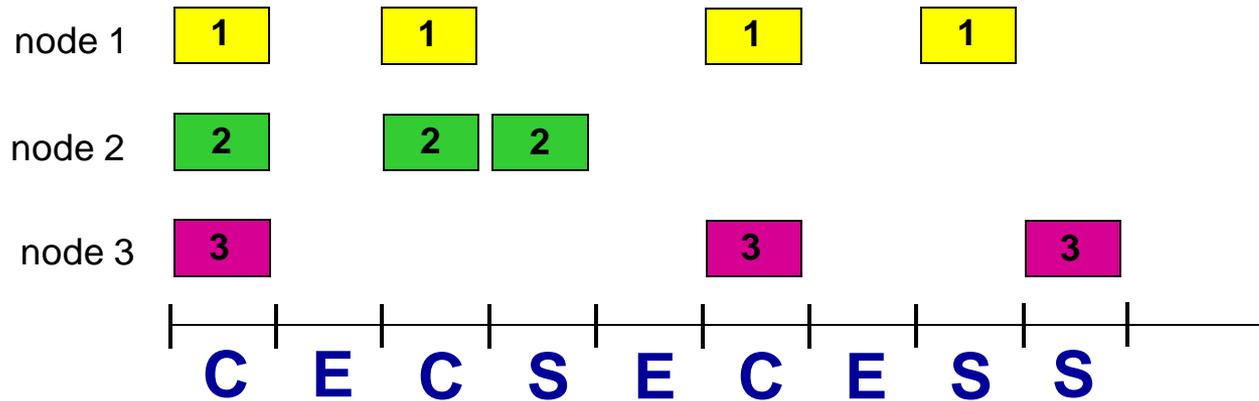
## *assumptions:*

- ❖ all frames same size
- ❖ time divided into equal size slots (time to transmit 1 frame)
- ❖ nodes start to transmit only slot beginning
- ❖ nodes are synchronized
- ❖ if 2 or more nodes transmit in slot, all nodes detect collision

## *operation:*

- ❖ when node obtains fresh frame, transmits in next slot
  - *if no collision:* node can send new frame in next slot
  - *if collision:* node retransmits frame in each subsequent slot with prob.  $p$  until success

# Slotted ALOHA



## Pros:

- ❖ single active node can continuously transmit at full rate of channel
- ❖ highly decentralized: only slots in nodes need to be in sync
- ❖ simple

## Cons:

- ❖ collisions, wasting slots
- ❖ idle slots
- ❖ nodes may be able to detect collision in less than time to transmit packet
- ❖ clock synchronization

# Slotted ALOHA: efficiency

**efficiency:** long-run fraction of successful slots (many nodes, all with many frames to send)

- ❖ suppose:  $N$  nodes with many frames to send, each transmits in slot with probability  $p$
- ❖ prob that given node has success in a slot =  $p(1-p)^{N-1}$
- ❖ prob that *any* node has a success =  $Np(1-p)^{N-1}$

- ❖ max efficiency: find  $p^*$  that maximizes  $Np(1-p)^{N-1}$
- ❖ for many nodes, take limit of  $Np^*(1-p^*)^{N-1}$  as  $N$  goes to infinity, gives:

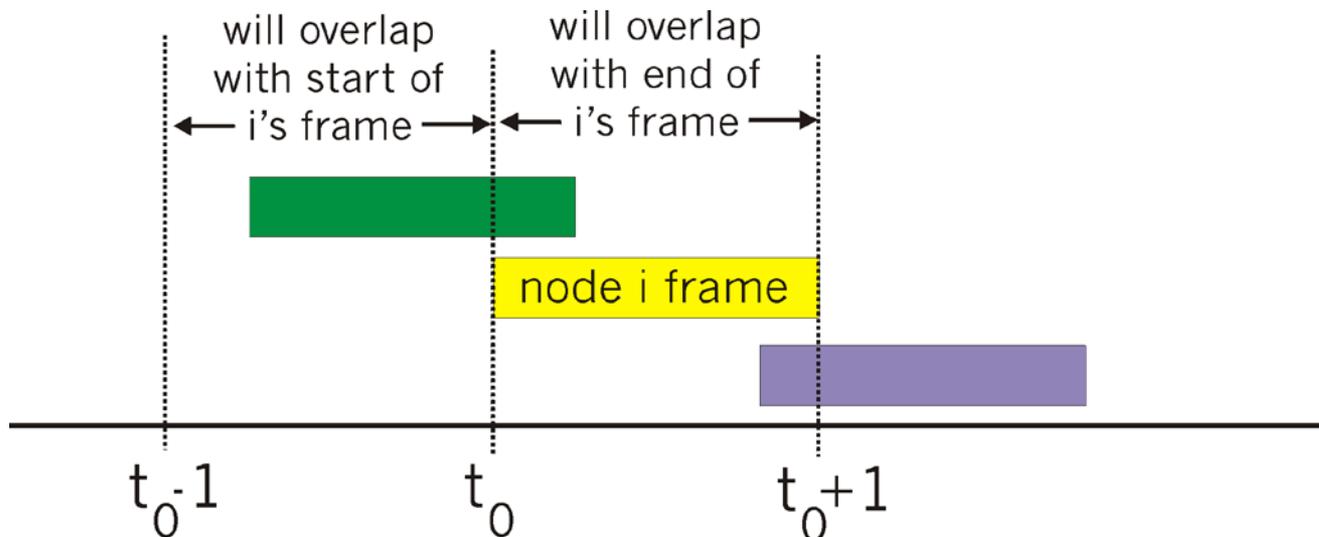
$$\text{max efficiency} = 1/e = .37$$

**at best:** channel used for useful transmissions 37% of time!



# Pure (unslotted) ALOHA

- ❖ unslotted Aloha: simpler, no synchronization
- ❖ when frame first arrives
  - transmit immediately
- ❖ collision probability increases:
  - frame sent at  $t_0$  collides with other frames sent in  $[t_0 - 1, t_0 + 1]$



# Pure ALOHA efficiency

$P(\text{success by given node}) = P(\text{node transmits}) \cdot$

$P(\text{no other node transmits in } [t_0-1, t_0]) \cdot$

$P(\text{no other node transmits in } [t_0-1, t_0])$

$$= p \cdot (1-p)^{N-1} \cdot (1-p)^{N-1}$$

$$= p \cdot (1-p)^{2(N-1)}$$

... choosing optimum  $p$  and then letting  $n \rightarrow \infty$

$$= 1/(2e) = .18$$

**even worse than slotted Aloha!**

# CSMA (carrier sense multiple access)

**CSMA:** listen before transmit:

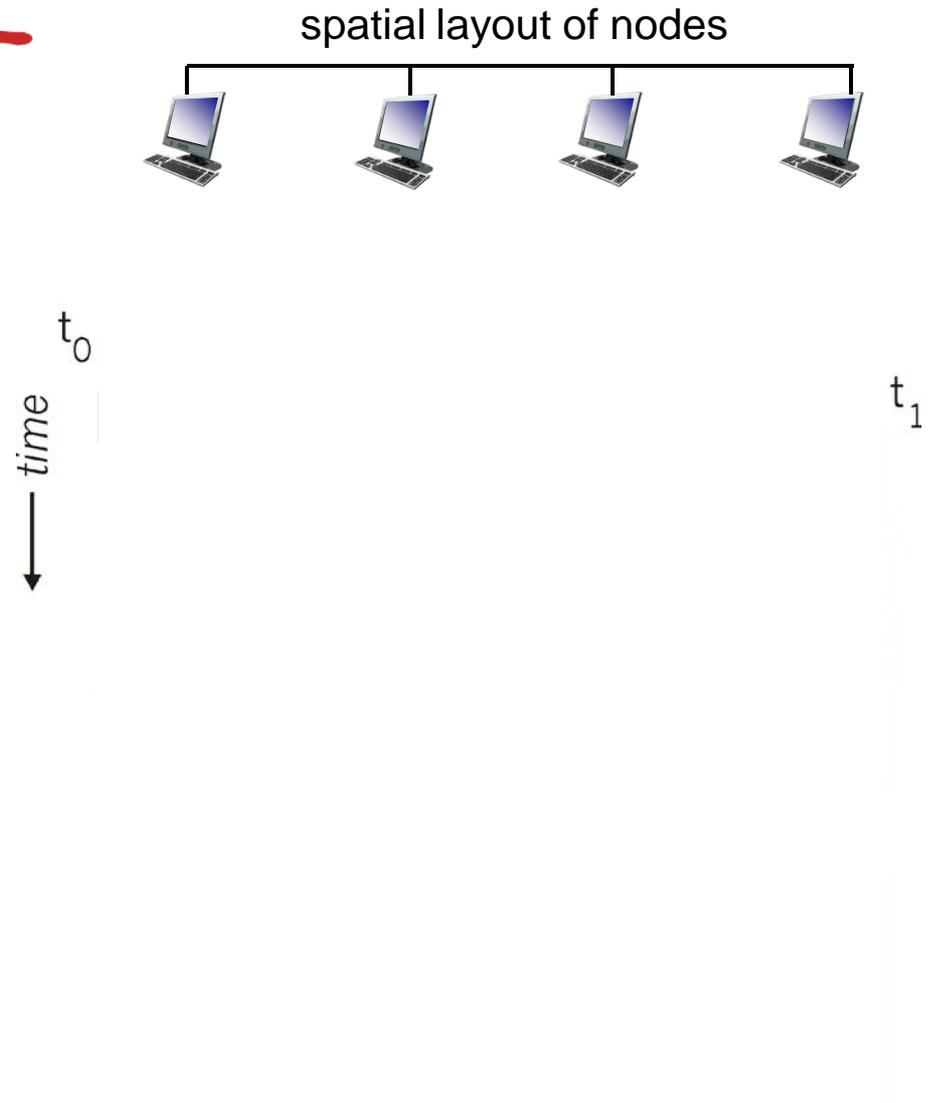
if channel sensed idle: transmit entire frame

❖ if channel sensed busy, defer transmission

❖ human analogy: don't interrupt others!

# CSMA collisions

- ❖ collisions *can* still occur: propagation delay means two nodes may not hear each other's transmission
- ❖ collision: entire packet transmission time wasted
  - distance & propagation delay play role in determining collision probability

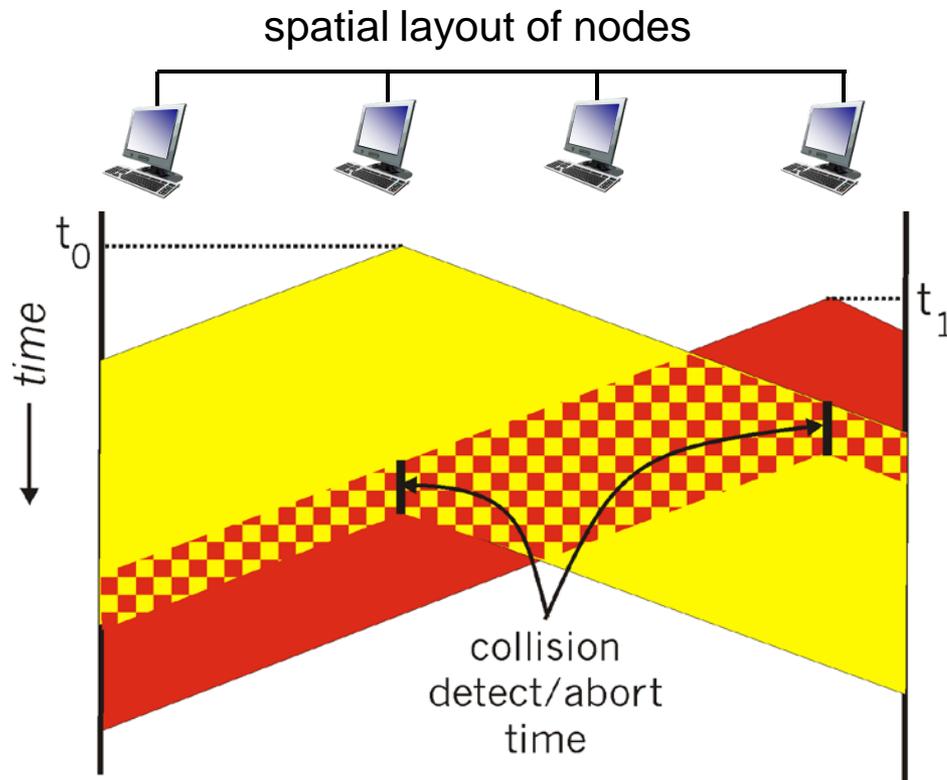


# CSMA/CD (collision detection)

**CSMA/CD:** carrier sensing, deferral as in CSMA

- collisions *detected* within short time
- colliding transmissions aborted, reducing channel wastage
- ❖ collision detection:
  - easy in wired LANs: measure signal strengths, compare transmitted, received signals
  - difficult in wireless LANs: received signal strength overwhelmed by local transmission strength
- ❖ human analogy: the polite conversationalist

# CSMA/CD (collision detection)



# Ethernet CSMA/CD algorithm

1. NIC receives datagram from network layer, creates frame
2. If NIC senses channel idle, starts frame transmission. If NIC senses channel busy, waits until channel idle, then transmits.
3. If NIC transmits entire frame without detecting another transmission, NIC is done with frame !
4. If NIC detects another transmission while transmitting, aborts and sends jam signal
5. After aborting, NIC enters *binary (exponential) backoff*:
  - after  $m$ th collision, NIC chooses  $K$  at random from  $\{0, 1, 2, \dots, 2^m - 1\}$ . NIC waits  $K \cdot 512$  bit times, returns to Step 2
  - longer backoff interval with more collisions

# CSMA/CD efficiency

- ❖  $T_{\text{prop}}$  = max prop delay between 2 nodes in LAN
- ❖  $t_{\text{trans}}$  = time to transmit max-size frame

$$\text{efficiency} = \frac{1}{1 + 5t_{\text{prop}}/t_{\text{trans}}}$$

- ❖ efficiency goes to 1
  - as  $t_{\text{prop}}$  goes to 0
  - as  $t_{\text{trans}}$  goes to infinity
- ❖ better performance than ALOHA: and simple, cheap, decentralized!

# Next class

- ❖ Please read Chapter 5.5 of your textbook **BEFORE**  
Class